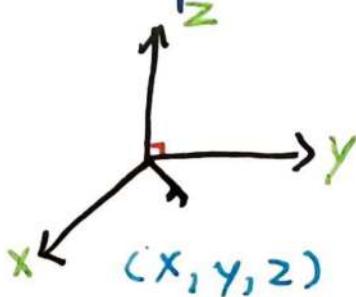
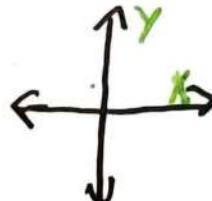


12.1 Coordinate in 3-Space

3-Space (\mathbb{R}^3)



2-Space (\mathbb{R}^2)



in :
"in" "such that"

I. Coordinate Planes

A Coordinate plane is the set of pts. in which a specified pt. is O (Ex. The xy -plane (aka the $z=0$) in \mathbb{R}^3 is $\Pi = \{P = (x, y, z) \in \mathbb{R}^3 : z = 0\}$, y^2 -plane in \mathbb{R}^3 $\{P = (x, y, z) : x = 0\}$, x^2 -plane in \mathbb{R}^3 $\{P = (x, y, z) \in \mathbb{R}^3 : y = 0\}$

Aside: Distances

m³

$$Q = (x_1, y_1, z_1)$$

$$P = (x_0, y_0, z_0) \quad \text{length} = \sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2 + (z_1 - z_0)^2}$$

$$d(P, Q) = \sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2 + (z_1 - z_0)^2}$$



$$d(P, Q) = \sqrt{(\Delta x)^2 + (\Delta y)^2}$$

← The Distance Formula (\mathbb{R}^3)

II Spheres

Let $r > 0$ and let $P \in \mathbb{R}^3$. The sphere of radius r centered at P is $S = \{Q \in \mathbb{R}^3 : d(P, Q) = r\}$. If P has coordinates $P = (x_0, y_0, z_0)$, then $S = \{Q \in \mathbb{R}^3 : d(P, Q) = r\} = \{(x_1, y_1, z_1) \in \mathbb{R}^3 : \sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2 + (z_1 - z_0)^2} = r\}$

NB: everything we've done so far has analogues solid ball is defined in higher dimensions. E.g., there is \mathbb{R}^4 by $(x, -x)^2 + (y, -y)^2 + (z, -z)^2 \leq r^2$ w/ a distance formula $\{ \mathbb{R}^4(x, y, z, w) : x, y, z, w \in \mathbb{R} \}$



NB: spheres are "surface" of a hollow ball

$$d(P, Q) = \sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2 + (z_1 - z_0)^2 + (w_1 - w_0)^2}$$

12.2: Vectors

Def: A vector in \mathbb{R}^2 is a directed line segment, where two vectors are equivalent when they are linear shifts

